

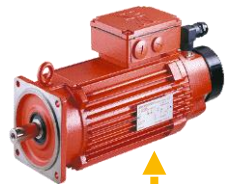


Co-funded by the  
Erasmus+ Programme  
of the European Union

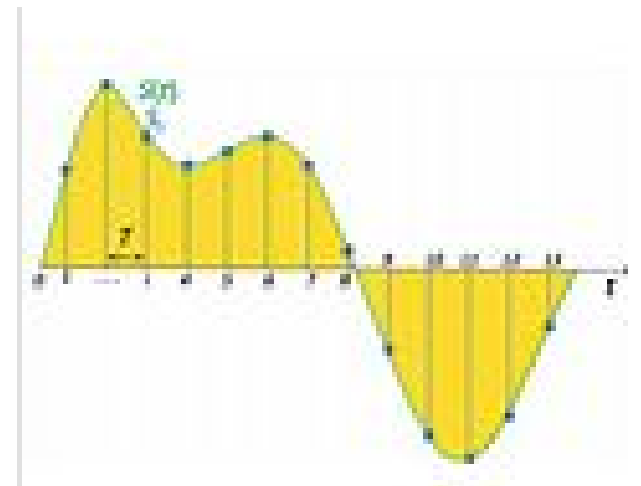
INDI 4.0

## PNOZmulti - Programming and Service

### Appendix A Speed and analogue modules



**PILZ**  
THE SPIRIT OF SAFETY



# ▶ Speed Monitoring Modules 1st generation



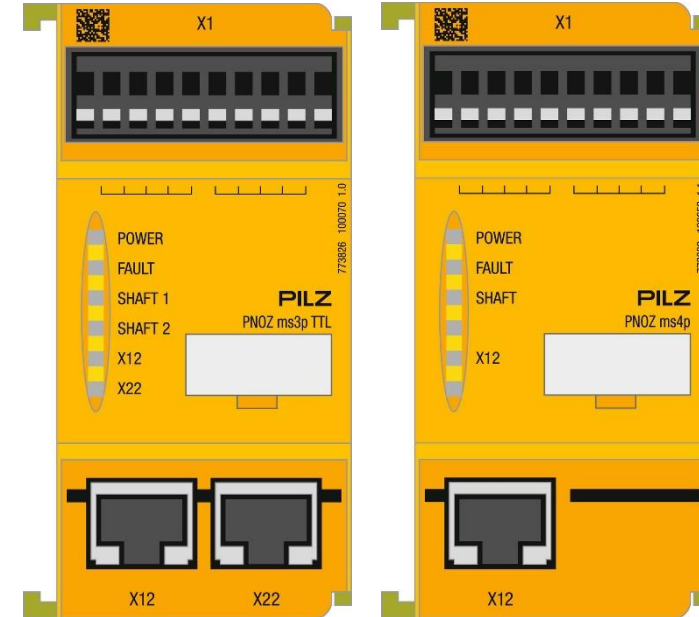
PILZ | A-2

## Speed module

Programming exercise motion monitoring

Analogue module

- ▶ Safe speed/standstill monitoring
  - 2 axes PL d / SIL CL 2
  - 1 axe PL e / SIL CL 3
- ▶ Proximity detectors (ms1p ... ms2p)
  - Up to 3 kHz
- ▶ or incremental encoders (ms1p ... ms4p)
  - Up to 500 kHz
- ▶ With direction recognition
- ▶ Independent monitoring of 2 axes per module
  - Maximum of 4 modules pluggable (4 modules = 8 axes)
- ▶ No external power supply required
  - Input signal of the encoder 0,5 ... 5 V, 0,5 ... 30 V or 12 ... 30 V



## ► Speed Modules 2nd generation



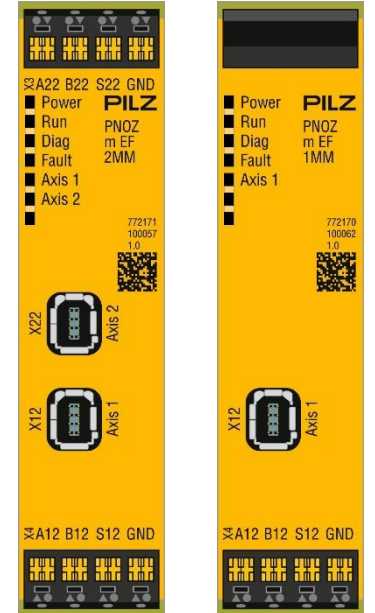
PILZ | A-2

### Speed module

Programming exercise motion monitoring

Analogue module

- Safe speed/standstill monitoring
  - 2 axes PL d / SIL CL 2
  - 1 axe PL e / SIL CL 3
- Proximity detectors
  - Up to 5 kHz
  - or incremental encoders
    - Up to 500 kHz
- With direction recognition
- Independent monitoring for 1 or 2 axes per module
  - Maximum of 6 modules pluggable (6 modules = 12 axes)



# ▶ Speed Modules

## 1st generation wiring example



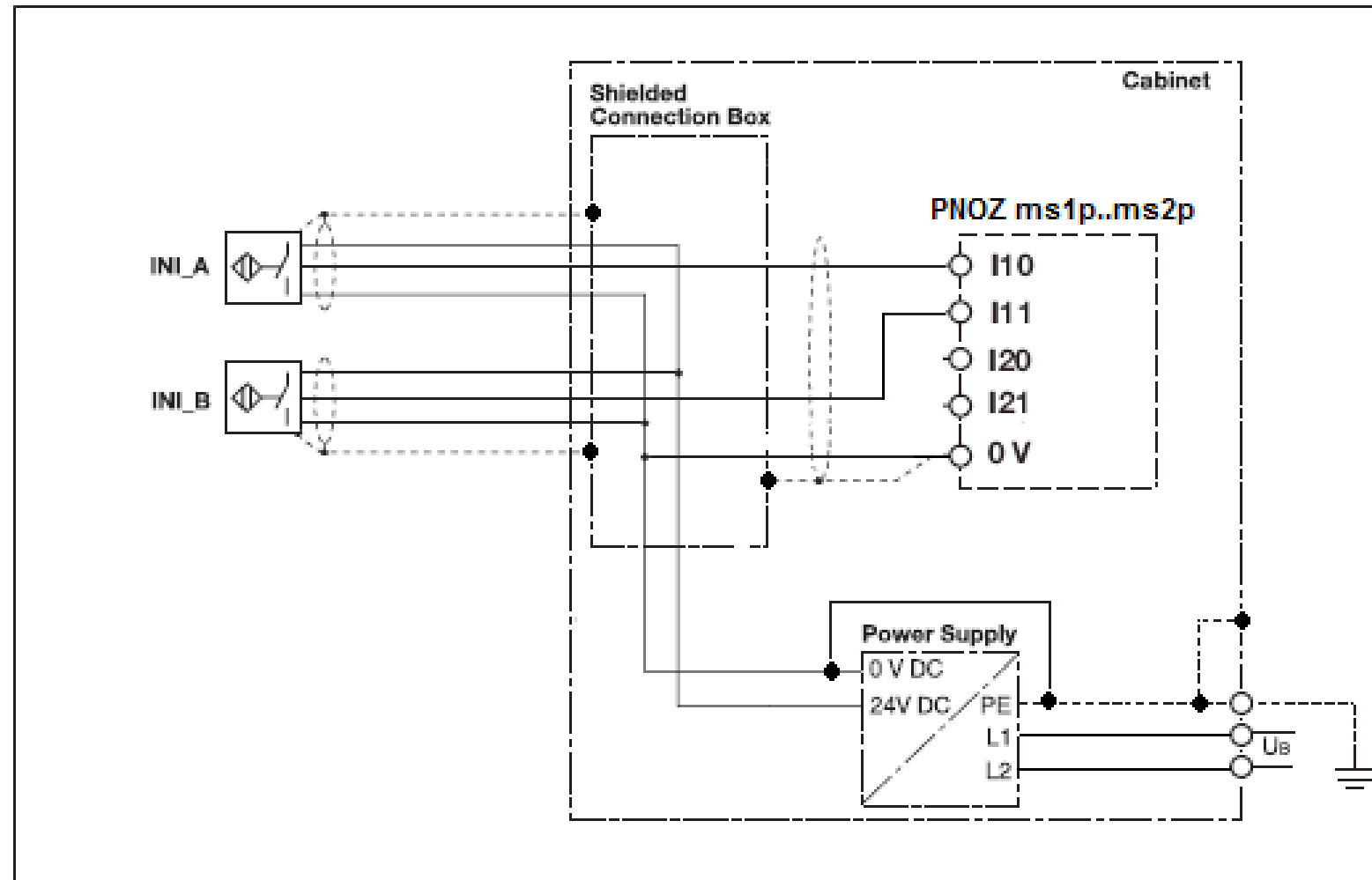
PILZ | A-5

### Speed module

Programming exercise motion monitoring

Analogue module

### ▶ Proximity switch with EMC-compliant wiring (PNOZ ms1p and ms2p)



# ► Speed Modules

## 1st generation wiring example



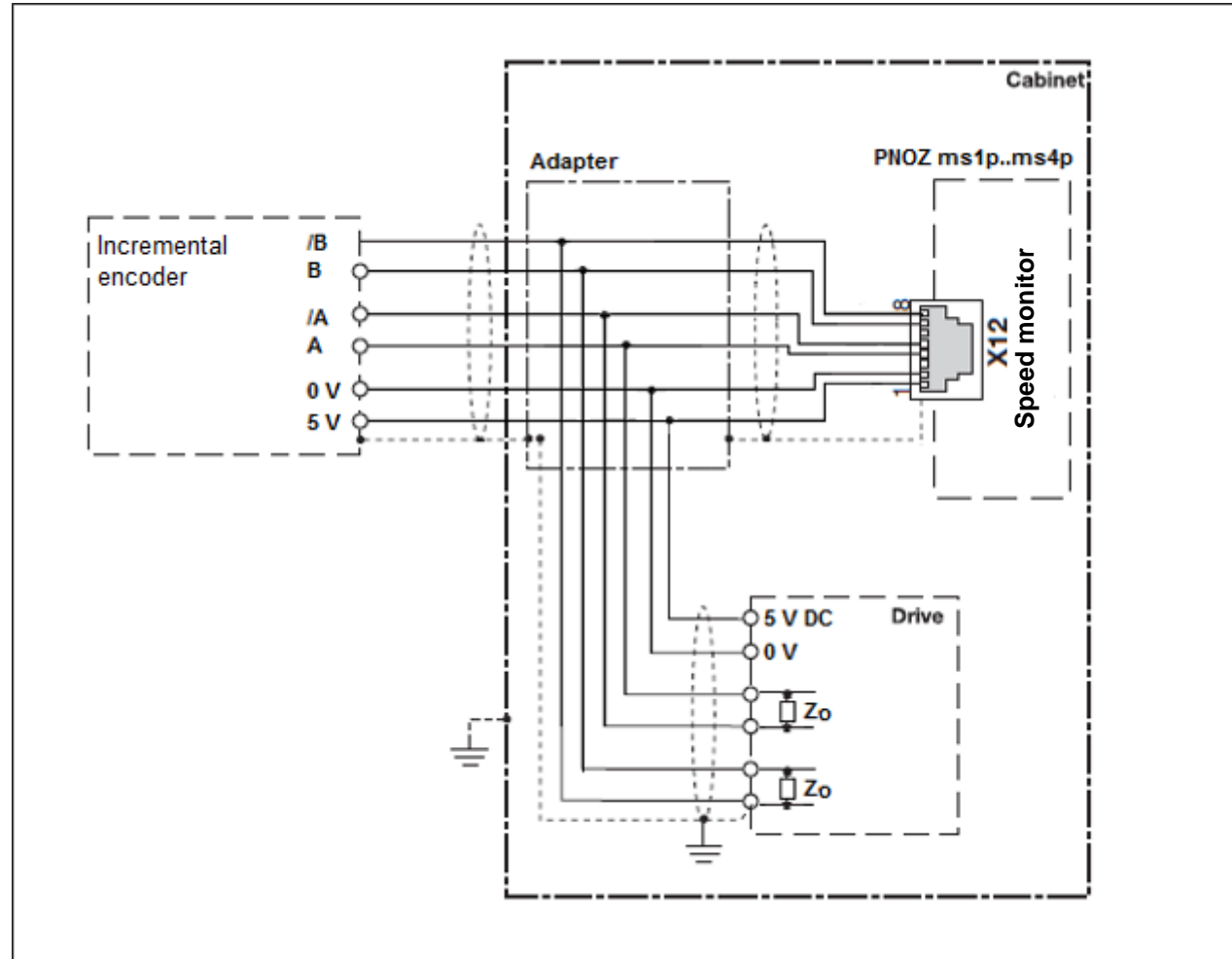
PILZ | A-5

### Speed module

Programming exercise motion monitoring

Analogue module

### ► Incremental encoder and drive with EMC-compliant wiring



# ► Speed Modules

## 1st generation encoder configuration



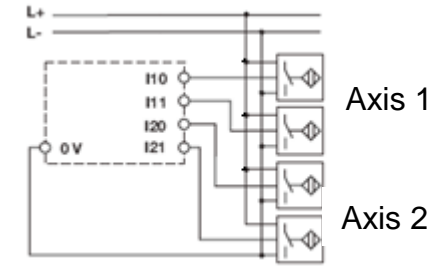
PILZ | A-6

### Speed module

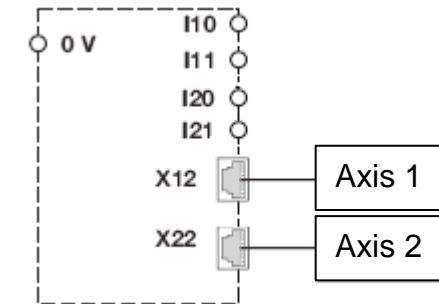
Programming exercise motion monitoring

Analogue module

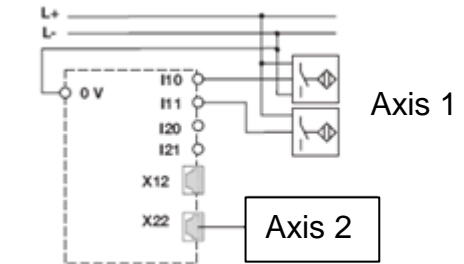
Axis 1 with two proximity switches to:  
- I10/I11.  
Axis 2 with two proximity switches to:  
- I20/I 21.



Axis 1 with one incremental encoder to:  
- X12.  
Axis 2 with one incremental encoder to:  
- X22.



Axis 1 with two proximity switches to:  
- I10/I11.  
Axis 2 with one incremental encoder to:  
- X22.



## ► Speed Modules

### 1st generation encoder configuration



PILZ | A-6

#### Speed module

Programming exercise motion monitoring

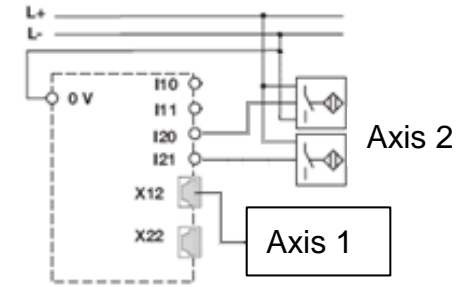
Analogue module

Axis 1 with one incremental encoder to:

- X12

Axis 2 with two proximity switches to:

- I20/I21



### Special configuration:

Axis 1 with one incremental encoder and one proximity switch to:

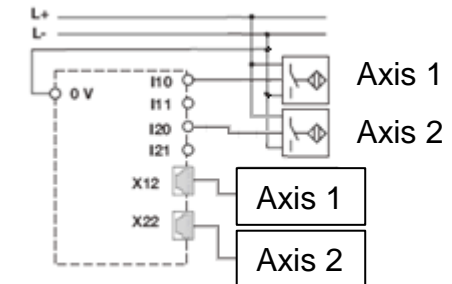
- X12 and

- I10 (I11 remains open).

Axis 2 with one incremental encoder and one proximity switch to:

- X22 and

- I20 (I21 remains open).



# ► Speed Modules

## 2nd generation wiring example



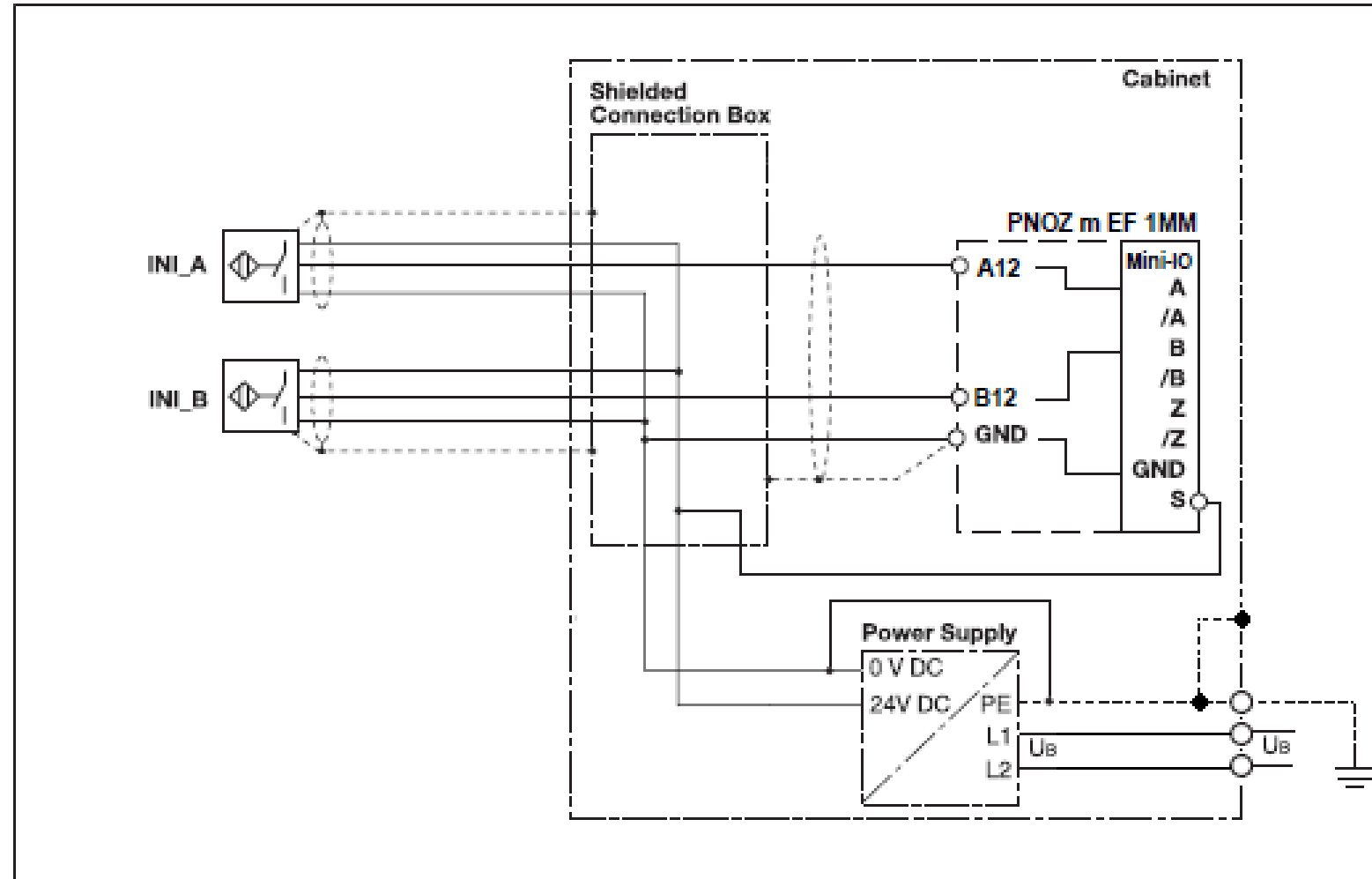
PILZ | A-7

### Speed module

Programming exercise motion monitoring

Analogue module

### ► Proximity switch with EMC-compliant wiring





# ▶ Speed Modules

## 2nd generation wiring example



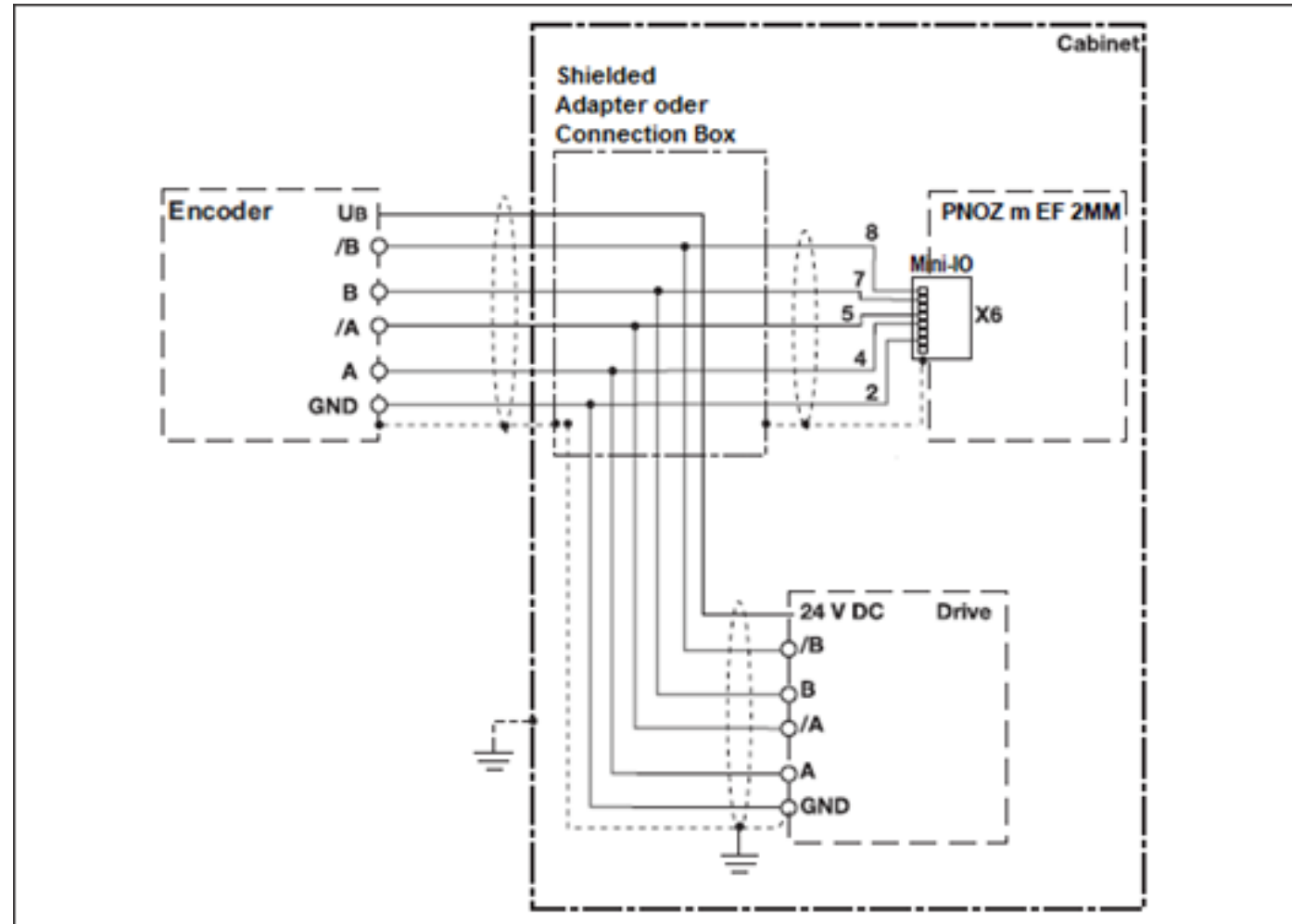
PILZ | A-7

### Speed module

Programming exercise motion monitoring

Analogue module

## ▶ Encoder and drive with EMC-compliant wiring



# ► Speed Modules

## 2nd generation encoder configuration



PILZ | A-8

**Speed module**

Programming exercise motion monitoring

Analogue module

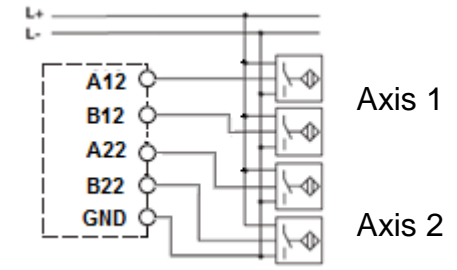
### PNOZ m EF 2MM:

Axis 1 with two proximity switches to:

- A12/B12

Axis 2 with two proximity switches to:

- A22/B22



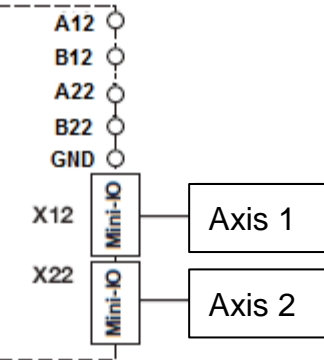
### PNOZ m EF 2MM:

Axis 1 with one encoder to:

- X12

Axis 2 with one encoder to:

- X22.



# ► Speed Modules

## 2nd generation encoder configuration



PILZ | A-8

### Speed module

Programming exercise motion monitoring

Analogue module

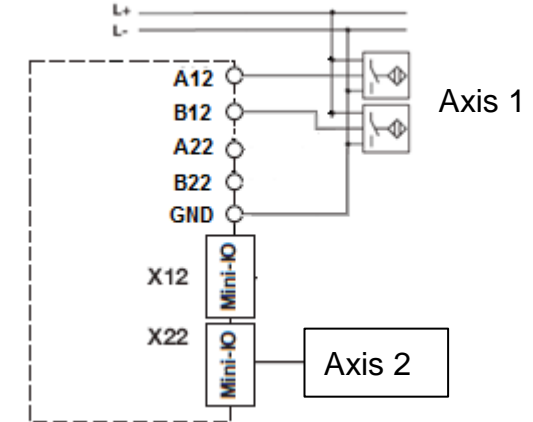
#### PNOZ m EF 2MM:

Axis 1 with two proximity switches to:

- A12/B12

Axis 2 with one encoder to:

- X22



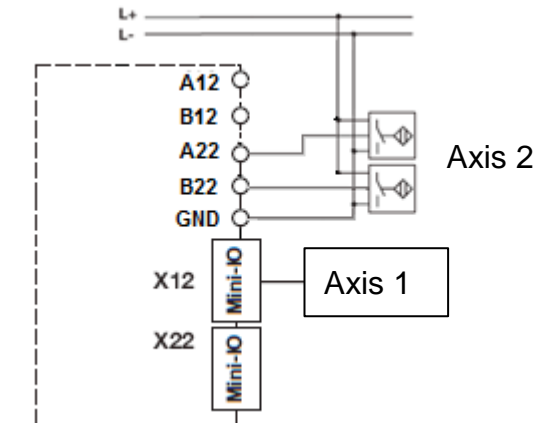
#### PNOZ m EF 2MM:

Axis 1 with one encoder to:

- X12

Axis 2 with two proximity switches to:

- A22/B22



# ► Speed Modules

## Special configuration



PILZ | A-9

Speed module

Programming exercise motion monitoring

Analogue module

### **PNOZ m EF 1MM..2MM:**

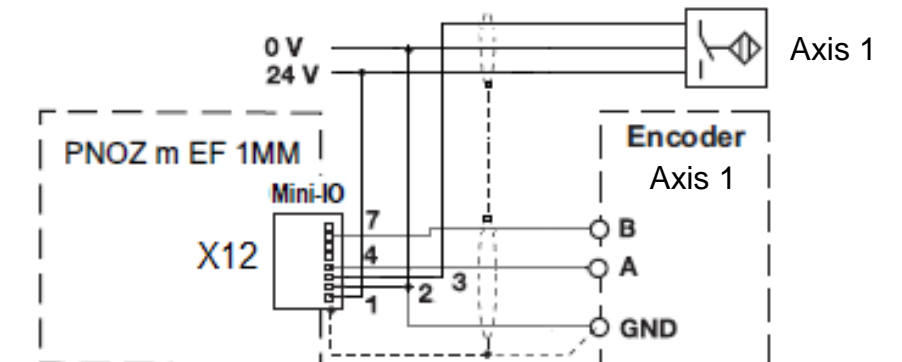
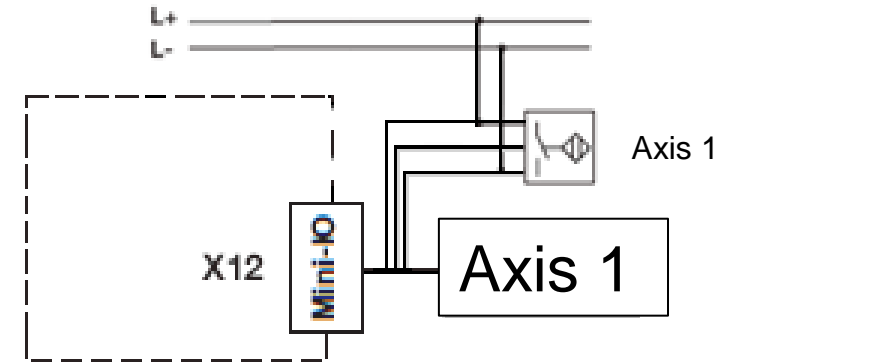
Axis 1 with one encoder and one proximity switch to:

- X12.

### **PNOZ m EF 2MM:**

Axis 2 with one encoder and one proximity switch to:

- X22.



# ► Speed Modules

## Proximity switch



PILZ | A-9

### Speed module

Programming exercise motion monitoring

Analogue module

PNOZ ms1p..ms4p (1st gen.)

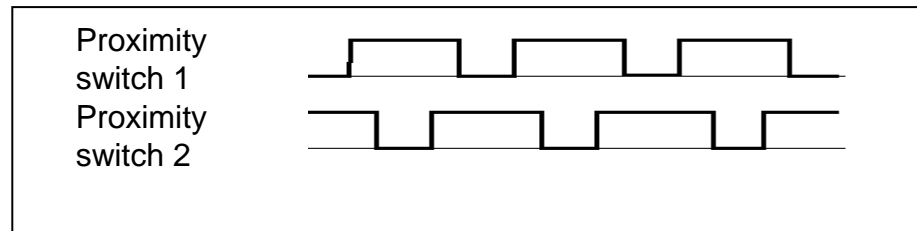
► **PNP** technology

PNOZ m EF 1MM..2MM (2nd gen.)

► **PNP/NPN** technology (*be freely selected*)

```

Hyperace + Z-frequenz ini pnp
Initiator A:npn, B:npn
Initiator A:npn, B:npn
Initiator A:npn, B:npn
Initiator A:npn, B:npn
    
```



One of the proximity switch must be damped

Proximity switch: **NO** (normally open)



Proximity switch: **NC** (normally closed)



# ► Speed Modules

## Incremental encoder / absolute encoder



PILZ | A-11

### Speed module

Programming exercise motion monitoring

Analogue module

Encoder	1st generation	2nd generation
Sin/Cos 1 V <sub>SS</sub> 500 kHz	PNOZ ms1p..ms4p	PNOZ m EF 1MM..2MM
TTL (RS 422) 500 kHz	PNOZ ms1p..ms4p	PNOZ m EF 1MM..2MM
HTL (24 V) 200 kHz	PNOZ ms2p..ms3p	-
HTL (24 V) 500 kHz	PNOZ ms4p	PNOZ m EF 1MM..2MM
Hiperface® (Absolutwertgeber)	-	PNOZ m EF 1MM..2MM

- TTL differenziell
- HTL Single Ended**
- HTL Single Ended + Z-Frequenz Ini pnp
- HTL Single Ended + Z-index
- HTL differenziell
- HTL differenziell + Z-Frequenz Ini pnp
- HTL differenziell + Z-index
- Hiperface
- Hiperface + Z-Frequenz Ini pnp
- Initiator A:nnp, B:nnp
- Initiator A:nnp, B:pnp
- Initiator A:pnp, B:nnp
- Initiator A:pnp, B:pnp
- Sin/Cos 1 V<sub>SS</sub>
- Sin/Cos 1 V<sub>SS</sub> + Z-Frequenz Ini pnp
- Sin/Cos 1 V<sub>SS</sub> + Z-index
- TTL Single Ended
- TTL Single Ended + Z-Frequenz Ini pnp
- TTL Single Ended + Z-index
- TTL differenziell
- TTL differenziell + Z-Frequency Ini pnp
- TTL differenziell + Z-index

## ▶ Speed Modules Adapter cable



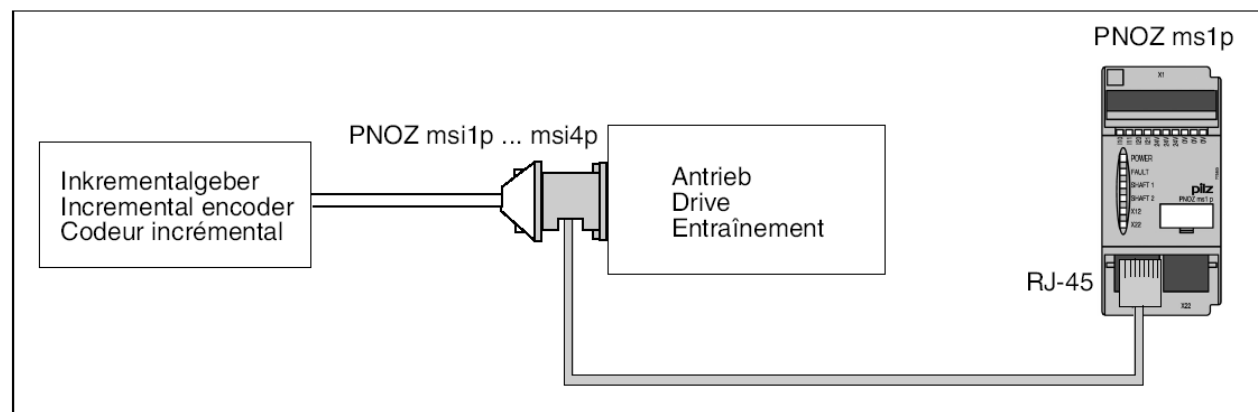
PILZ | A-11

### Speed module

Programming exercise motion monitoring

Analogue module

- ▶ For connection of encoders:
  - to-PNOZ ms1p ... ms4p and PNOZ m EF 1MM..2MM
- ▶ Use of available donor
- ▶ Various adapters are available for commonly used:
  - Servo amplifier
  - Incremental encoder
  - Absolute encoder
- ▶ Variable cable lengths



# Speed Modules

## Adapter cable



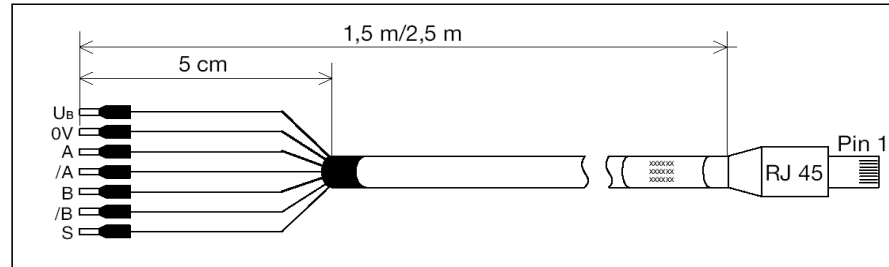
PILZ | A-12

**Speed module**

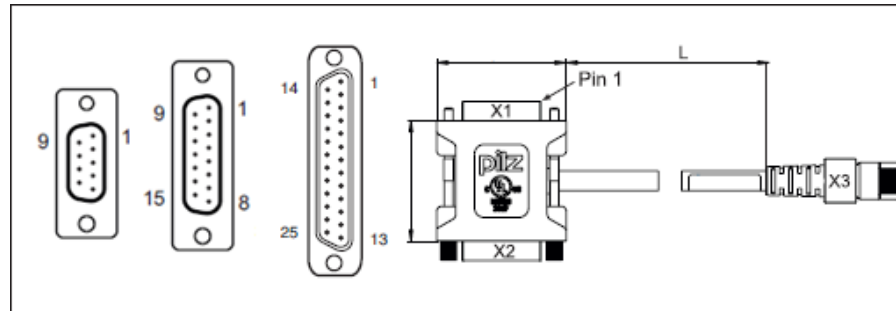
Programming exercise motion monitoring

Analogue module

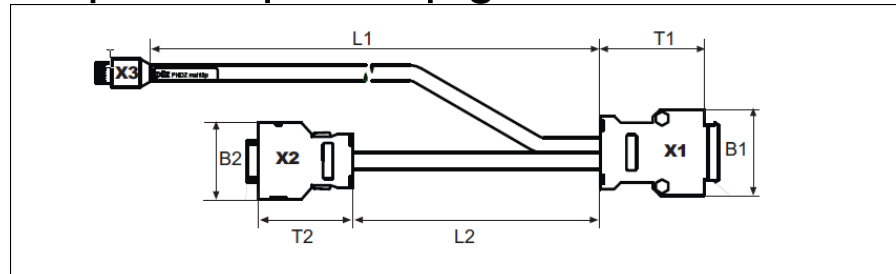
Universal adapter:



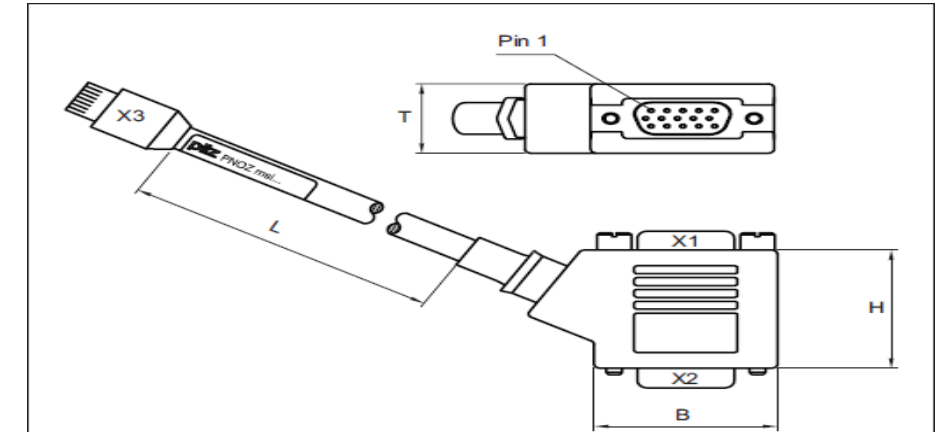
9-, 15- or 25-pin adapter:



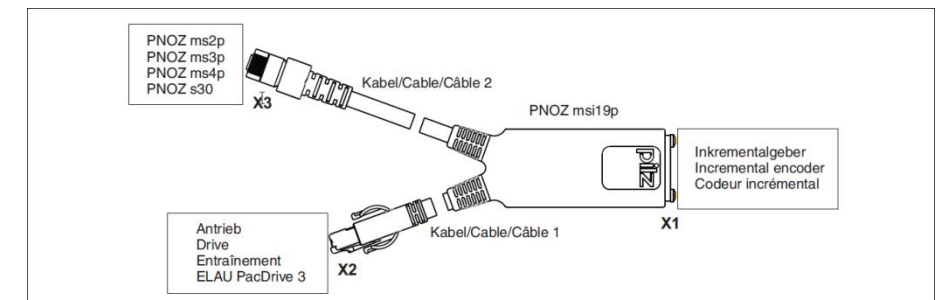
20-pin adapter in pigtail version:



25-pin adapter



RJ-45 adapter in pigtail version





# ► Overview of the Motion Monitor Elements

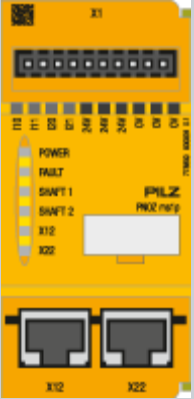


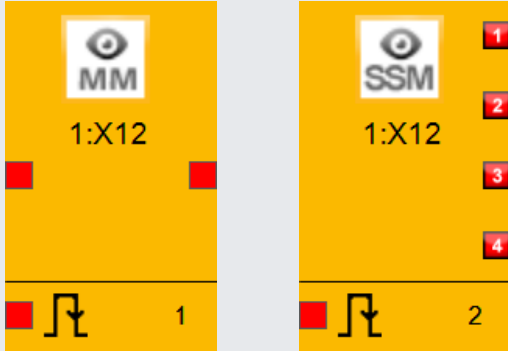


PILZ | A-15

## Speed module

Programming exercise motion monitoring

Analogue module

Motion module	Title	Elements
	<p>PNOZ ms1p                      PNOZ ms2p                      PNOZ ms3p                      PNOZ ms4p                      PNOZ ms2p HTL                      PNOZ ms3p HTL                      PNOZ ms2p TTL                      PNOZ ms3p TTL</p>	
	<p>PNOZ m EF 1MM (up to V 1.1)                      PNOZ m EF 2MM (up to V 1.1)</p>	

# ► Overview of the Motion Monitor Elements

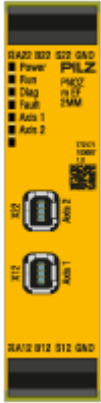
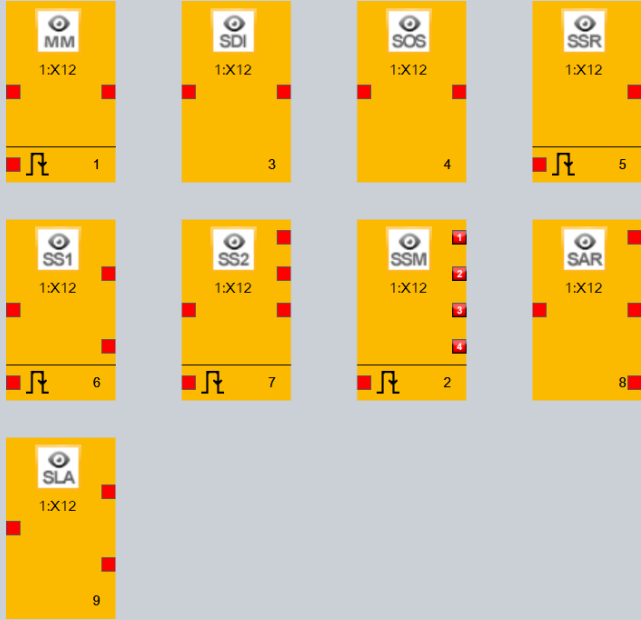


PILZ | A-15

## Speed module

Programming exercise motion monitoring

Analogue module

Motion Module	Title	Elements
	<p>PNOZ m EF 1MM (from V 2.0) PNOZ m EF 2MM (from V 2.0)</p>	<p>In the module program:</p> 

# ► PNOZ m EF 1MM..2MM (2nd Generation) „SDI-M (Safe Direction Monitoring)“



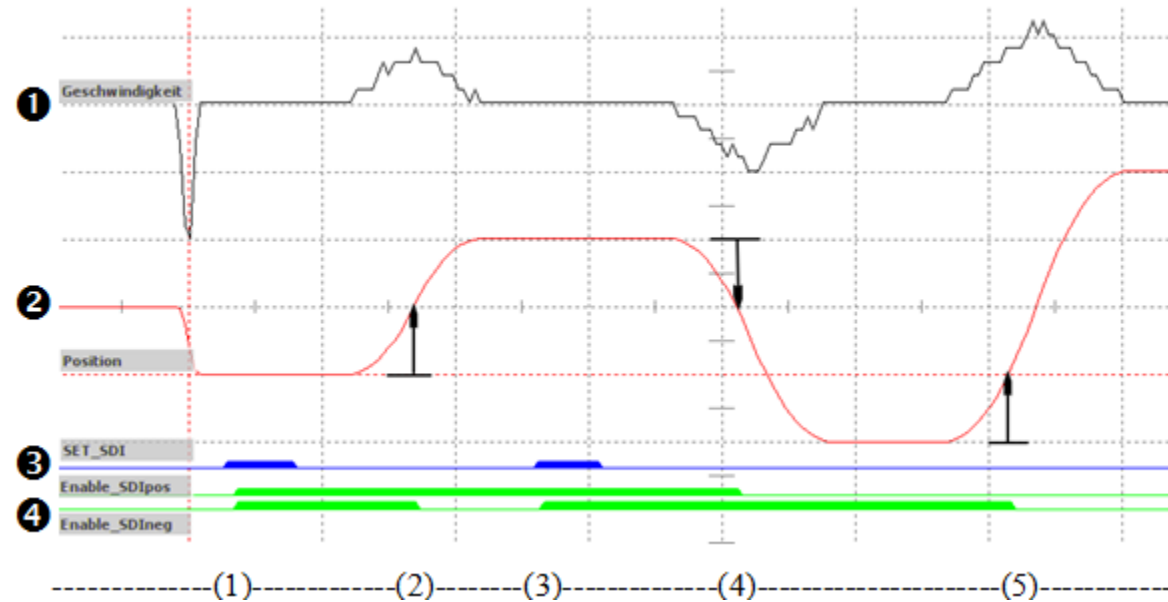
PILZ | A-24

## Speed module

Programming exercise motion monitoring

Analogue module

The SDI-M function prevents the motor shaft moving in the unintended direction (EN 61800-5-2).



Line ❶: Actual speed [5000 incr/div.]  
 Line ❷: Actual position [1000 incr/div.]  
 Line ❸: SET\_SDI  
 Line ❹: Enable SDIpos/SDImeg  
 Time axis: 1000 ms/div.

(1): With a rising edge SET\_SDI, the enables SDIpos and SDIneg are switched on.  
 (2): Tolerance is exited in the positive direction, SDIneg is reset.  
 (3): Post-triggering with SET\_SDI is possible at any time.  
 (4): Tolerance is exited in the negative direction, SDIpos is reset.  
 (5): Tolerance is exited in the positive direction, SDIneg is also reset.

# ▶ PNOZ m EF 1MM..2MM (2nd Generation) „SOS-M (Safe Operating Stop Monitoring)“



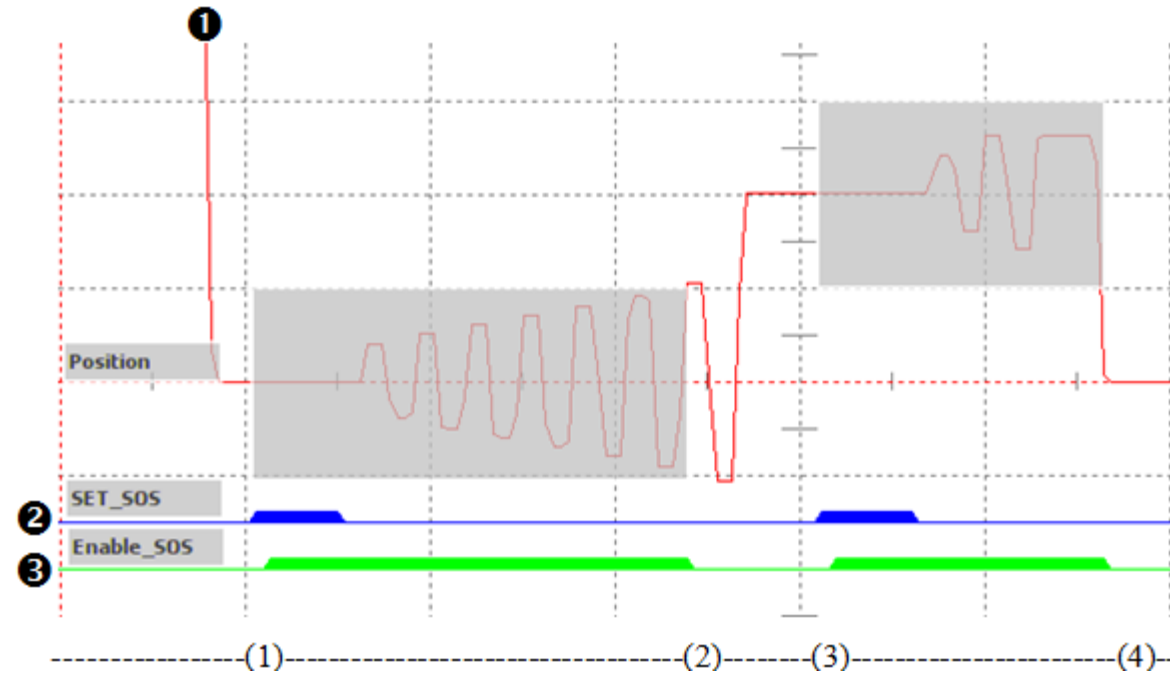
PILZ | A-25

## Speed module

Programming exercise motion monitoring

Analogue module

The SOS-M function prevents the motor deviating by more than a defined amount from the stop position (EN 61800-5-2).



Line ❶: Actual position [50 incr/div.]  
 Line ❷: SET\_SOS  
 Line ❸: Enable SOS  
 Time axis: 1000 ms/div

(1): The tolerance band is set with SET\_SOS  
 (2): The actual position leaves the tolerance band  
 (3): The tolerance band is set again  
 (4): The actual position leaves the tolerance band

# ▶ PNOZ m EF 1MM..2MM (2nd Generation) „SSR-M, Safe Speed Range Monitoring“



PILZ | A-26

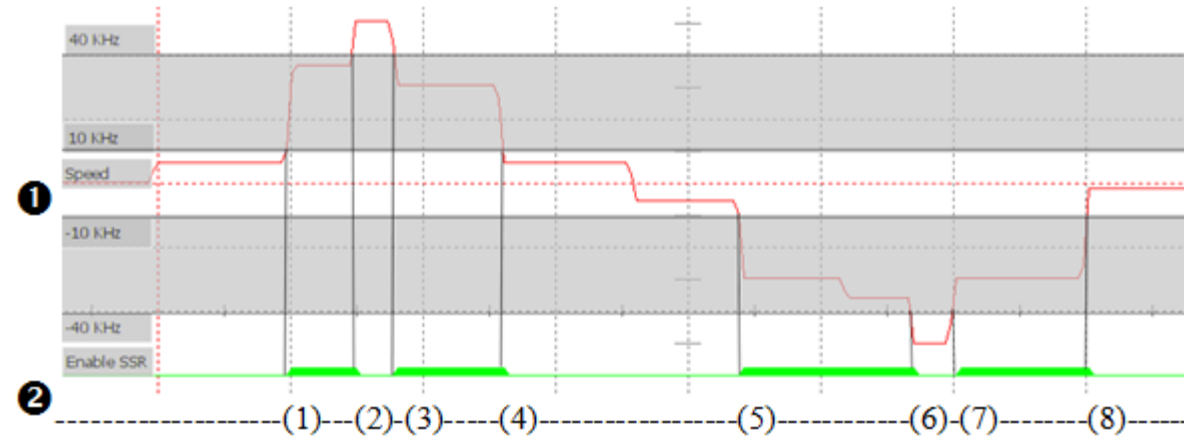
## Speed module

Programming exercise motion monitoring

Analogue module

The SSR-M function keeps the motor speed within the defined limits (EN 61800-5-2).

### ▶ Example 1: Hysteresis = 0 %



Line ❶: Speed [10 kHz/div.]  
Line ❷: Enable SSR-M  
Time axis: 1000 ms/div

(1): Speed in the positive range  
(2): Speed above the upper positive limit  
(3): Speed in the positive range  
(4): Speed below the lower positive limit  
(5): Speed in the negative range  
(6): Speed below the lower negative limit  
(7): Speed in the negative range  
(8): Speed above the upper negative limit

# ► PNOZ m EF 1MM..2MM (2nd Generation) „SSR-M, Safe Speed Range Monitoring“



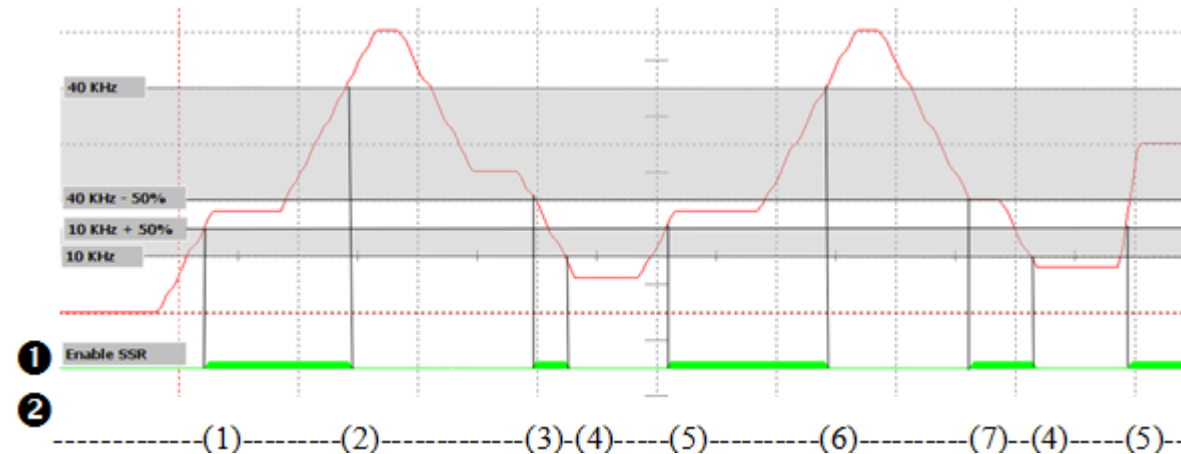
PILZ | A-27

## Speed module

Programming exercise motion monitoring

Analogue module

## Example 2: Hysteresis = 50 %



Line ❶: Speed [10 kHz/div.]  
Line ❷: Enable SSR-M  
Time axis: 1000 ms/div

(1): Speed > lower limit + 50%  
(2): Speed > upper limit  
(3): Speed < upper limit - 50%  
(4): Speed < lower limit  
(5): Speed > lower limit + 50%  
(6): Speed > upper limit  
(7): Speed < upper limit - 50%

# ▶ PNOZ m EF 1MM..2MM (2nd Generation) „SSR-M, Safe Speed Range Monitoring“



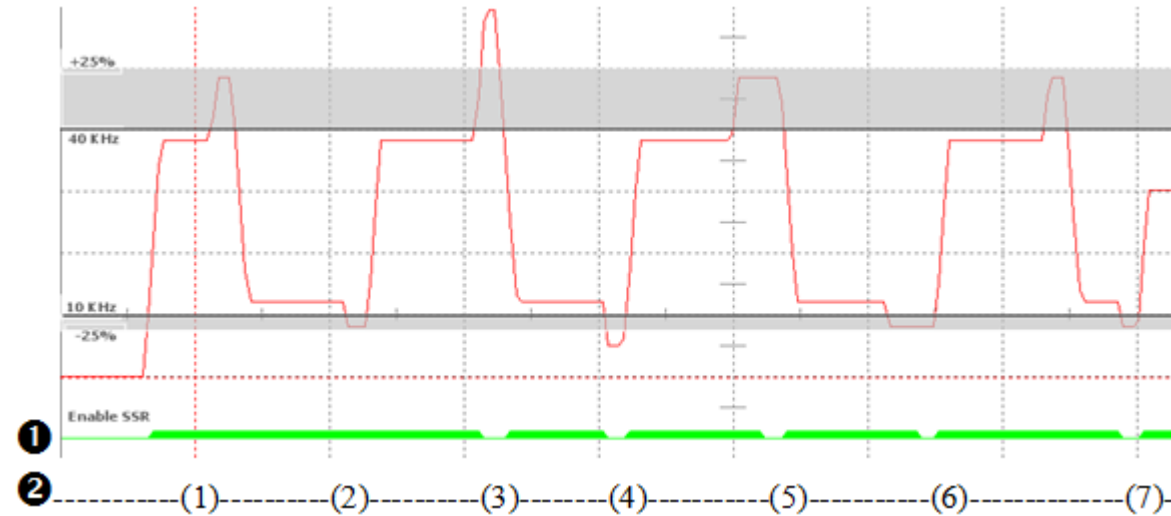
PILZ | A-28

## Speed module

Programming exercise motion monitoring

Analogue module

## ▶ Example 3: Activated tolerance range



Line ❶: Speed [10 kHz/div.]  
Line ❷: Enable SSR-M  
Time axis: 1000 ms/div

(1): Overshoots within the tolerance time  $t_1$  and the tolerance amount  
(2): Overshoots within the tolerance time  $t_1$  and the tolerance amount  
(3): Tolerance amount exceeded  
(4): Tolerance amount exceeded  
(5): Tolerance time  $t_1$  exceeded  
(6): Tolerance time  $t_1$  exceeded  
(7): Two overshoots within the tolerance period  $t_2$ .

# ▶ PNOZ m EF 1MM..2MM (2nd Generation) „SSM (Safe Speed Monitoring)“



PILZ | A-29

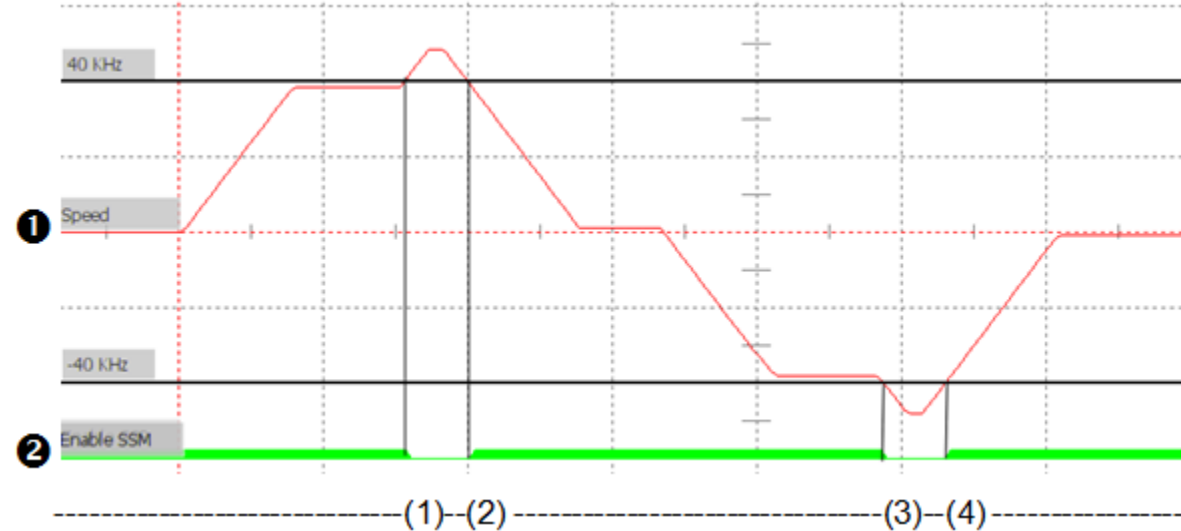
## Speed module

Programming exercise motion monitoring

Analogue module

The SSM function delivers a safe signal to indicate whether the motor speed lies below or above a defined limit (EN 61800-5-2).

### ▶ Example 1: Hysteresis = 0 %



Line ❶: Speed [20 kHz/div.]  
Line ❷: Enable SSM  
Time axis: 1000 ms/div

(1): Speed exceeds the positive limit  
(2): Speed falls below the positive limit  
(3): Speed falls below the negative limit  
(4): Speed exceeds the negative limit



# ▶ PNOZ m EF 1MM..2MM (2nd Generation) „SSM (Safe Speed Monitoring)“



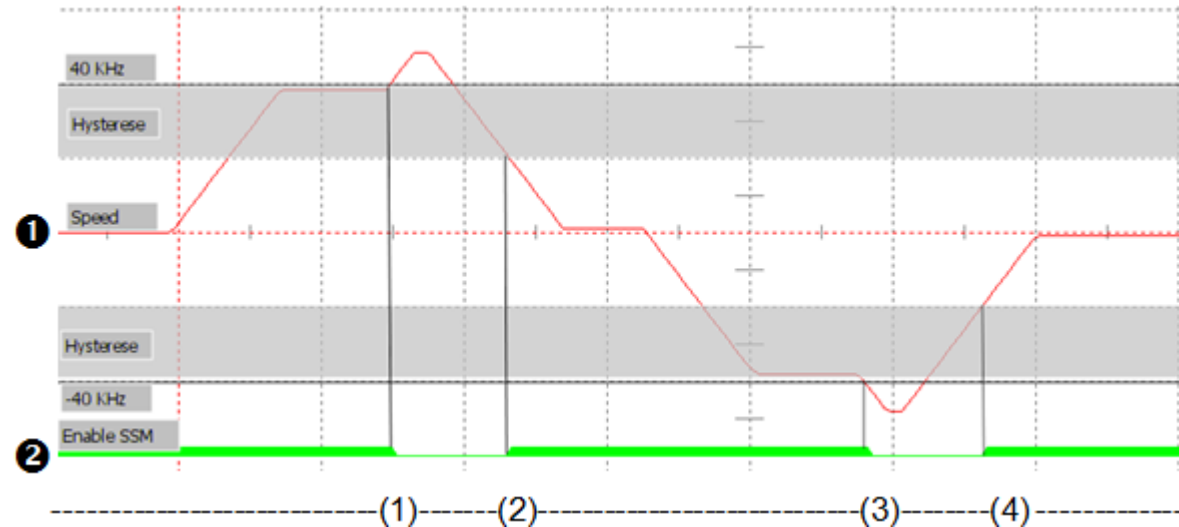
PILZ | A-30

## Speed module

Programming exercise motion monitoring

Analogue module

### ▶ Example 1: Hysteresis = 50 %



Line ❶: Speed [20 kHz/div.]  
Line ❷: Enable SSM  
Time axis: 1000 ms/div

(1): Speed exceeds the positive limit  
(2): Speed falls below the positive limit minus hysteresis  
(3): Speed falls below the negative limit  
(4): Speed exceeds the negative limit plus hysteresis

# ▶ PNOZ m EF 1MM..2MM (2nd Generation) „SSM (Safe Speed Monitoring)“



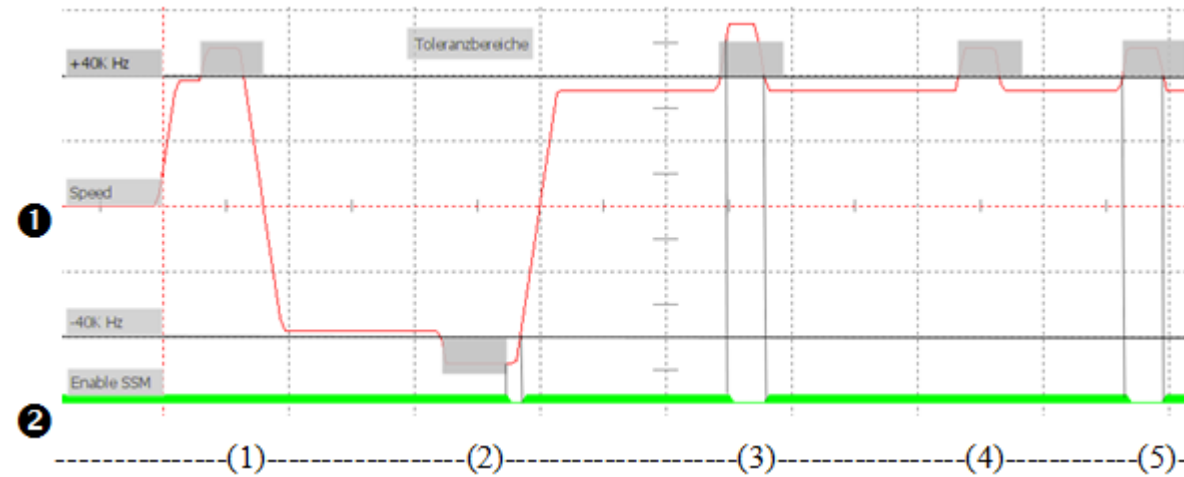
PILZ | A-31

## Speed module

Programming exercise motion monitoring

Analogue module

## ▶ Example 2: Activated tolerance range



Line ❶: Speed [20 kHz/div.]  
Line ❷: Enable SSM  
Time axis: 1000 ms/div.

- (1): The speed remains within the defined tolerance range.
- (2): The tolerance time  $t_1$  is exceeded.
- (3): The tolerance amount  $Tol$  is exceeded.
- (4): The speed remains within the defined tolerance range.
- (5): The tolerance period  $t_2$  has not been observed

# ► Programming Exercise Speed Modules

## Spezifikation



PILZ | A-34

Speed module

**Programming exercise motion monitoring**

Analogue module

No.	Description	PLr	Max. Reaction time	Priority
SF1	E-STOP (-4S1) (as in programming exercise no. 2)	d	100 ms	High
SF2	E-STOP (-6S1) (as in programming exercise no. 2)	d	100 ms	High
SF3	Safety gate (as in programming exercise no. 2)	d	100 ms	Med.
SF4	Light curtain (as in programming exercise no. 2)	d	40 ms	Med.
SF5	<b>Operating mode selector switch:</b> <b>OFF: No operating selected (as E-STOP)</b> <b>Automatic mode: Motor speed is not monitored</b> <b>Manual mode: Motor speed is monitored</b>	d	100 ms	High
SF6	<b>Motion monitoring:</b> <b>If the motor speed in “Manual mode” exceeds the maximum permitted speed, the motor is switched off.</b> <b>Hysteresis 50 %.</b> <b>Reset with neg. edge is required.</b>	d	100 ms	Med.

# ► Programming Exercise Speed Modules Spezifikation



PILZ | A-34

Speed module

**Programming exercise motion monitoring**

Analogue module

No.	Description	PLr	Max. Reaction time	Priority
SF7	<b>Enabling switch: In manual mode, the drive can run with the enabling switch when the safety gate is open and/or the light curtain is actuated. Motor speed is monitored.</b>	-	100 ms	High
ZF1	Plant stop (as in programming exercise no. 1)	-	100 ms	Low_2
ZF2	Plant stop (as in programming exercise no. 1)	-	100 ms	Low_2
ZF3	Light in the start button (as in programming exercise no. 1)	-	100 ms	Low_3

# ► Programming Exercise Speed Modules

## Cause and Effect-Matrix



PILZ | A-35

Speed module

Programming exercise motion monitoring

Analogue module

		Cause										Effect													
		Involved Inputs										Safety function					Outputs					Verification		Validation	
Operating mode AUTO (SF5)	Operatin mode manual (SF5)	Previous state no. during test	State no.	4S1.E-STOP_Ch1 (SF1)	4S1.E-STOP_Ch2 (SF1)	6S1.E-STOP_Ch1 (SF2)	6S1.E-STOP_Ch2 (SF2)	Safety_gate_Ch1 (SF3)	Safety_gate_Ch2 (SF3)	Light_Curtain_Ch1 (SF4)	Light_Curtain_Ch1 (SF4)	Motion-Monitoring (SF6)	Enable Button (SF7)	Reset (Reset plant)	Reset (Reset Safety gate)	Contactor K1	Contactor K2	Lamp in the start button	Checked (ok / not ok)	Checked (ok / not ok)					
1	0	-	1	1	1	1	1	1	1	1	1	1	0			ON	ON	ON							
1	0	1	2	0	0	1	1	1	1	1	1	1	0			ON	ON	ON							
1	0	1	3	1	1	1	1	1	1	1	1	1	0	YES	NO	OFF	OFF	OFF							
1	0	1	4	1	1	1	1	0	0	1	1	1	0	YES	NO	OFF	OFF	OFF							
1	0	1	5	1	1	1	1	1	1	0	0	1	0	NO	YES	OFF	OFF	OFF							
1	0	1	6	1	1	1	1	1	1	1	1	1	0	YES	NO	ON	ON	ON							
0	1	1	7	1	1	1	1	1	1	1	1	1	0			ON	ON	ON							
0	1	7	8	0	0	1	1	1	1	1	1	1	0	YES	NO	OFF	OFF	OFF							
0	1	7	9	1	1	0	0	1	1	1	1	1	0	YES	NO	OFF	OFF	OFF							
0	1	7	10	1	1	1	1	0	0	1	1	1	0	NO	YES	OFF	OFF	OFF							
0	1	7	11	1	1	1	1	1	1	0	0	0	0	NO	NO	OFF	OFF	OFF							
0	1	7	12	1	1	1	1	0	0	1	1	0	1	NO	YES	ON	ON	ON							
0	1	7	13	1	1	1	1	1	1	0	0	0	1	NO	NO	OFF	OFF	OFF							
V1		Date:																							
V1		Name:																							
D1		Validation performed (ok / not ok):																							
D1		Date:																							
D1		Name:																							

# ► Programming Exercise Speed Modules

## Cause and Effect-Matrix



PILZ | A-36

Speed module

Programming exercise motion monitoring

Analogue module

Main program	Function description	Graphic
<p>Page 1 (SF)</p>	<p>Safety function: If one of the E-STOP devices is operated or the safety gate is opened or the light curtain is actuated, the enable for power to the drive contactors is removed.</p> <p><b>NEW:</b>  <b>Operating mode selector switch with the operating modes:</b></p> <ul style="list-style-type: none"> <li>- OFF (as E-STOP)</li> <li>- MANUAL</li> <li>- AUTOMATIC</li> </ul> <p>and the enabling switch.</p> <p>In <b>MANUAL</b> mode, the enabling switch can be used to run the drive at max. 200 1/min even if the safety gate is open and/or the light curtain is actuated.</p>	<p>The graphic shows various PILZ safety devices: two yellow E-stop buttons (one with a red stop button), two yellow light curtains (PSEN 2-1p-10 and PSEN 2-1-10), a PNOZmulti safety relay module with four indicator lights (1, 2, 3, 4), and a black enabling switch with a key. The text 'or' is placed between the PNOZmulti module and the enabling switch.</p>

# ► Programming Exercise Speed Modules

## Cause and Effect-Matrix





PILZ | A-36

Speed module

**Programming exercise motion monitoring**

Analogue module

Main program	Function description	Graphic
Page 2 (Start-Stop)	<p>The machine drive can be switched on using the start button and switched off using the stop button.</p> <p>The enable for the safety functions must be present.</p> <p>The drive contactors are monitored using a feedback loop (EDM).</p>	
Module program_1	Function description	Graphic
Page 1 (SSM)	<p><b>The speed is to be monitored at 200 revolutions per minute (1/min) with the SSM element. This is only monitored in “Manual” mode.</b></p>	

# ▶ Analogue Module 1st Generation General



PILZ | A-37

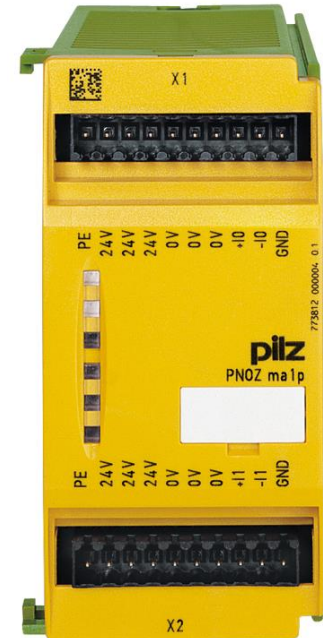
Speed module

Programming exercise motion  
monitoring

**Analogue module**

## Features

- ▶ Module is connected to the left page
- ▶ 2 safety analog inputs
  - IEC 62061: SIL CL 2
  - ISO 13849-1: PL d
- ▶ Monitoring of current or voltage
- ▶ Up to 4 modules can be connected to the base unit left = 8, analog inputs
- ▶ Condition
  - Hardware: PNOZmulti base unit up to V 5.6
  - Software: PNOZmulti Configurator up to V 5.3.0





# ► Analogue Module 1st Generation Wiring



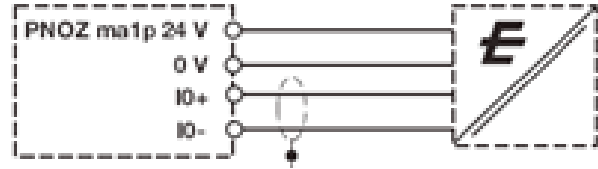
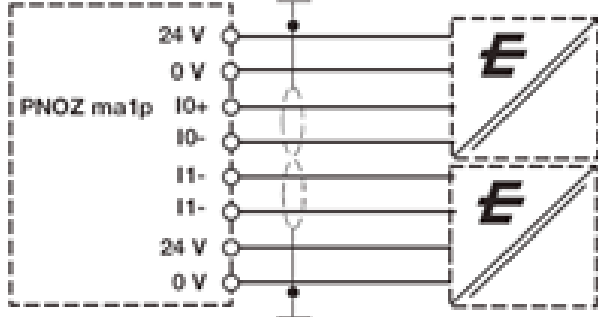
PILZ | A-38

Speed module

Programming exercise motion monitoring

**Analogue module**

## ► Current measurement

Application in accordance with: - PL d - SIL 2	
Application in accordance with: - PL e - SIL 3	

## ► Voltage measurement

- No examples for voltage measurement
- The signal to be measured must be connected to the analogue input
- Pay attention to shielding

# ► Analogue Module 1st Generation

## Software elements




PILZ | A-39

Speed module

Programming exercise motion monitoring

**Analogue module**

Illustration	Name	Description and setting options
	Analogue	<p>Input element for processing the analog signals of the PNOZ m a1p module.</p> <p>This element has the following functions:</p> <ul style="list-style-type: none"><li>- Tolerance and current equivalent</li><li>- Area monitoring</li><li>- Threshold monitoring</li><li>- Restart behavior</li></ul>

# ► Analogue Module 1st Generation

## Software elements



PILZ | A-41

Speed module

Programming exercise motion monitoring

**Analogue module**

- Only one element: analogue element
- Placement in the left column in the main program
- All settings are made in the module
  - Range monitoring to configure the expected input signal
  - Threshold value monitoring for configuring the switching thresholds

**Eingangselement konfigurieren**

Eingangselement: **Analogeingangselement**

Eingänge Bereichsüberwachung Schwellenwertüberwachung Start Allgemein PVIS

Einstellungen  
Spezifizieren Sie bitte den Bereich der Eingangswerte.

Fehler, wenn

Bedingung	Werte (Bereich: 0 ... 25,59)[mA]	Kommentar
R1: <	3	
R2: >	22	
R3:		
R4:		

Schwellenwertüberwachung

0 mA 2 4 6 8 10 12 14 16 18 20 22 24 25,59 mA

■ überwachter Bereich  
■ unüberwachter Bereich

OK Abbrechen Hilfe

**Eingangselement konfigurieren**

Eingangselement: **Analogeingangselement**

Eingänge Bereichsüberwachung Schwellenwertüberwachung Start Allgemein PVIS

Skalieren

	Min.	Max.	Einheit
<input checked="" type="radio"/> Skaliert	3	22	mA
<input type="radio"/> Unskaliert	0	100	kg

Strom: Physikalischer Wert

Ausgangssignale  
Werte eingeben im Bereich 0,0 ... 100,0 kg

Setzen, wenn	Zurücksetzen, wenn	Kommentar		
Bedingung	Wert [kg]	Bedingung	Wert [kg]	
L1: >	90	<	85	Palette voll, Palette tauschen
L2: >	95	<	85	Fehler: Palette überladen
L3:				
L4:				
L5:				
L6:				
L7:				
L8:				

OK Abbrechen Hilfe

# ► Analogue Module 2nd Generation

## General



PILZ | A-43

Speed module

Programming exercise motion monitoring

**Analogue module**

### Features

- Module is connected to the right page
- 4 safety analog inputs
  - IEC 62061: SIL CL 2
  - ISO 13849-1: PL d
- Monitoring of current
- Up to 6 (PNOZ m B0 = 24 analog inputs) or 12 (PNOZ m B1 = 48 analog inputs) modules can be connected to the base unit
- Condition
  - Hardware: PNOZmulti base unit up to V 2.5 (PNOZ m B0)
  - Software: PNOZmulti Configurator up to V 10.8.0



# ▶ Analogue Module 2nd Generation Wiring



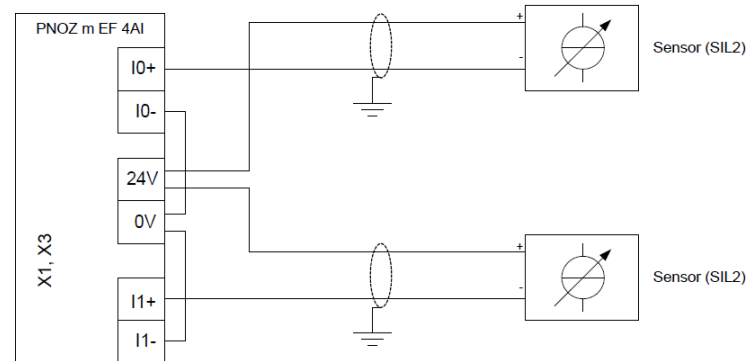
PILZ | A-44

Speed module

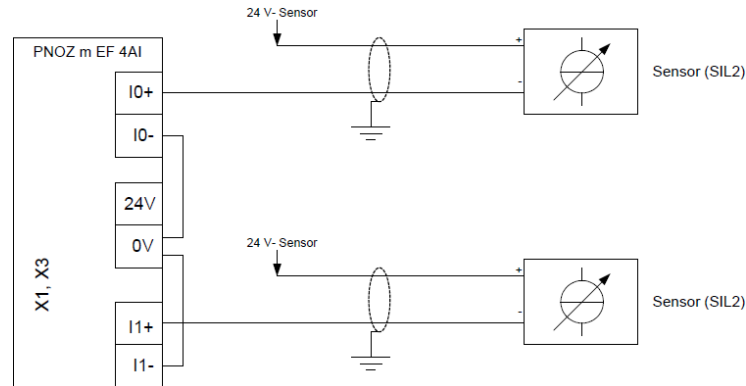
Programming exercise motion monitoring

**Analogue module**

- ▶ 2-wire connection, voltage supplied to the sensors via analogue input module



- ▶ 2-wire connection, voltage supplied to the sensors externally



# ► Analogue Module 2nd Generation Wiring



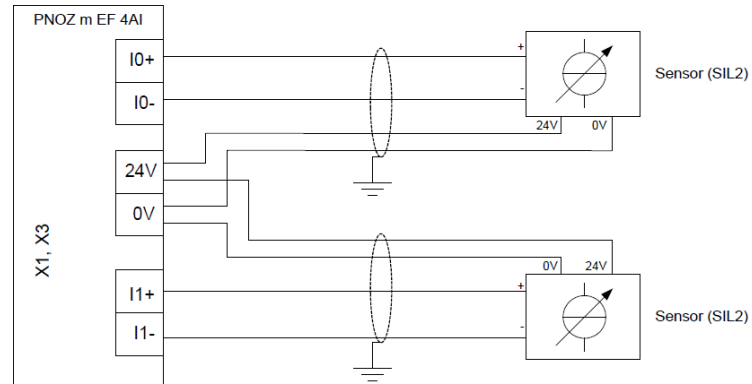
PILZ | A-45

Speed module

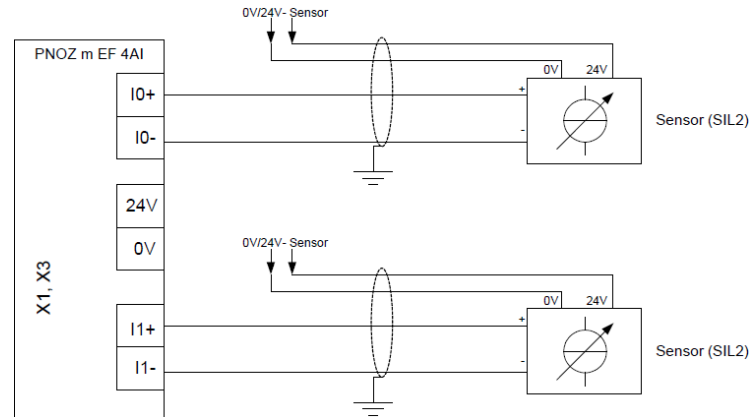
Programming exercise motion monitoring

**Analogue module**

- 4-wire connection, voltage supplied to the sensors via analogue input module



- 4-wire connection, voltage supplied to the sensors externally



# ► Analogue Module 2nd Generation Software elements



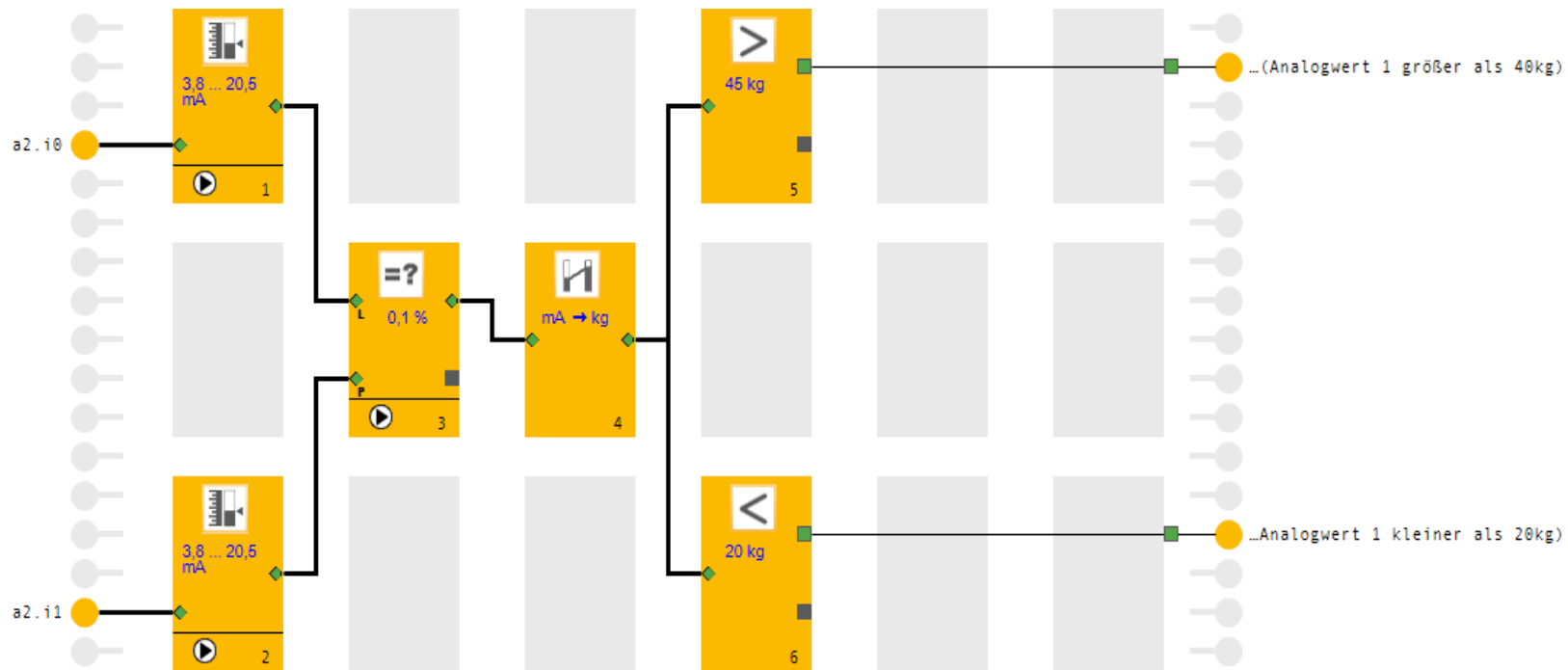
PILZ | A-46

Speed module

Programming exercise motion monitoring

**Analogue module**

- Several elements:
  - Analog input element
  - Billing and calculation elements
  - Area monitoring elements



# ► Analogue Module 2nd Generation

## Software elements

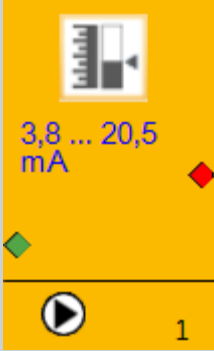
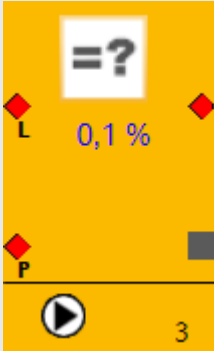


PILZ | A-49

Speed module

Programming exercise motion monitoring

**Analogue module**

Illustration	Name	Description and setting options
	<p>Analogue input element</p>	<p>Function element for processing the analogue signals of the module PNOZ m EF 4AI.</p> <p>This element has the following functions:</p> <ul style="list-style-type: none"> <li>- Tolerance and current equivalent</li> <li>- Working range monitoring</li> <li>- Restart behaviour</li> </ul>
	<p>Plausibility</p>	<p>Function element for connecting two analogue input elements with integrated plausibility test. The deviation of both values is monitored.</p> <p>Tolerance types:</p> <ul style="list-style-type: none"> <li>-Percentage tolerance</li> <li>-Absolute tolerance</li> <li>-Absolute/percentage tolerance</li> </ul> <p>A temporary deviation of the value can also be set via the “Peak Tolerance” tab. A tolerance time and a tolerance period can be set.</p>



# ► Analogue Module 2nd Generation

## Software elements

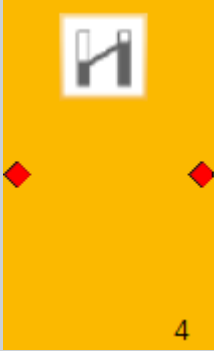
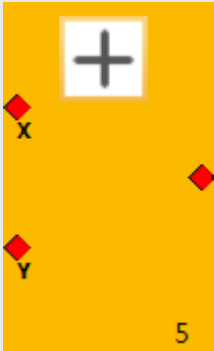


PILZ | A-49

Speed module

Programming exercise motion monitoring

**Analogue module**

Illustration	Name	Description and setting options
	<p>Scaling</p>	<p>The scaling block is used to convert the input value into an output value. The current, checked for plausibility, is configured on the input side; the scaled limit values are set on the output side. The unit of the configured value is also entered. This will be set and displayed automatically in all subsequent elements.</p>
	<p>Mathematical operation</p>	<p>The input value X is offset with the input value Y via a mathematical function. The following mathematical functions are available:</p> <ul style="list-style-type: none"> <li>- Addition</li> <li>- Subtraction</li> <li>- Average</li> </ul>

# ► Analogue Module 2nd Generation

## Software elements


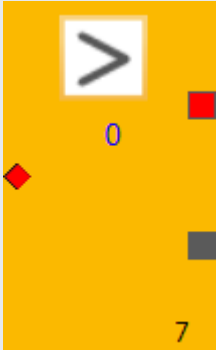


PILZ | A-50

Speed module

Programming exercise motion monitoring

**Analogue module**

Illustration	Name	Description and setting options
	<p>Constant</p>	<p>The constant element allows a consistent variable constant to be added in mathematical operations. A constant can have a positive or negative sign.</p>
	<p>Range monitoring</p>	<p>Range monitoring is used to monitor analogue words. These may or may not have been calculated. One threshold is monitored per element via the conditions</p> <ul style="list-style-type: none"> <li>- Greater than</li> <li>- Less than</li> </ul> <p>The switch-on and switch-off threshold can be set separately.</p> <p>This element serves as the interface between the analogue values and the main program's binary system. Only its output can be connected to a program connector output.</p>

## Automatisierungs- technik

COMPONENTS  
SYSTEMS  
SERVICES

innovativ    ökologisch  
sicher        wirtschaftlich

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